Participatory Design of Socially Assistive Robots for Preventive Patient-Centered Healthcare*

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Abstract—This paper presents an ongoing project using participatory design methods to develop socially assistive robots (SARs) for older adults diagnosed with depression and co-occurring physical illness. We frame SARs development in the context of preventive patient-centered healthcare, which empowers patients as the primary drivers of health and aims to delay the onset of disease rather than focusing on treatment. We describe how SARs can be of particular benefit in this new direction in healthcare, and detail our participatory design study with older adults and therapists aimed at developing preventive SARs applications for this population.

I. INTRODUCTION

Recent years have seen the proliferation of socially assistive robots (SARs) for the purposes of improving the functioning and quality-of-life (QOL) of people who experience chronic and age-related health issues [1, 2]. Many SARs-related studies occur in either laboratory or institutionalized care settings (e.g. nursing homes) and focus on treatment and rehabilitation. However, “health” is not something that happens once someone gets sick or diagnosed; it is the result of an accumulating cascade of daily choices and environmental factors. Impacting health in daily life – prior to the development of illness or the need for institutionalized care (i.e. preventative healthcare) – represents a novel opportunity for exploring applications of assistive robotics, and brings up the need to understand how robots may fit into peoples’ everyday lives and within the growing focus on patient-centered care.

A noteworthy example is clinical depression in the elderly. Depression is the 2nd leading cause of disability in the United States [3], and a particularly prevalent problem among older adults. Mental health issues such as depression often precipitate the emergence of physical health problems and/or decline in physical functioning, resulting in the need for institutionalized care. Institutionalized care is far more expensive than in-home care [4]. Moreover, most elderly prefer to remain independently living in their own homes for as long as possible. Thus, the current paradigm neither meets the needs of individual users nor benefits society at large.

Research in laboratory and institutional settings suggests that interactive robots and sensors can support and enhance the social, cognitive, and physical functioning of older adults [1, 5, 6]. Our current project, presented here, explores how SARs could be implemented in the homes of older adults before they become institutionalized, with the aim of preventing or delaying the need for such institutionalization. The participants are independently living older adults diagnosed with clinical depression and co-occurring physical illness. To address the social challenges of developing and deploying assistive robotic technologies in this setting (and to fit within the paradigm of patient-centered care), we use participatory design (PD) with relevant stakeholders – older adults, therapists, and case workers. The aim is to provide a better understanding of appropriate designs, deployment methods, uses, and effects of SARs that can lead to more successful technical and social outcomes.

We describe our motivation for examining SARs for preventive healthcare applications and how we use PD to develop appropriate ways of implementing SARs in the homes of older adults. The ultimate goal of the project is to understand 1) how SARs can best be used for prevention of the development of health issues in real world settings, and 2) how we can better incorporate user needs and concerns into SARs design and deployment strategies.

II. BACKGROUND AND MOTIVATION

A. Depression Incidence and Treatment in Older Adults

The Institute of Medicine’s 2012 report on mental health in older adults estimates that currently at least 5.6-8 million, (nearly one in five) older adults in the US experience a mental illness, and that by 2030 that number will rise to between 10.1-14.4 million [7]. Clinical depression affects 15-20% of older adults in the US [8]. Depression in the elderly entails intensive treatment, which is often inconsistently provided and/or provided in clinical settings (e.g. primary care doctor’s office) that may not be the most appropriate. The IOM 2012 report suggests the field leverage technology to improve care and access to care in this population.

SAR technologies hold potential to address this IOM recommendation. One particular area in which SARs stand to
be beneficial is in addressing loneliness, which the literature reveals to be a key component of depression in the elderly and an independent risk factor for physical/cognitive decline in this population (see Section II.C) [9]. Research with the therapeutic robot PARO in institutionalized settings has shown that robots can be used to help alleviate feelings of loneliness in older adults [10], suggesting SARs could provide therapeutic benefits that reduce symptoms of clinical depression in older adults living independently as well.

B. Socially Assistive Robots in Eldercare

Socially assistive robots (SARs) are an emerging technology envisioned as having widespread applications in eldercare [1], including physical assistance and measurable behavioral, cognitive, or therapeutic effects. Research has shown that the therapeutic effects of SARs on the elderly can include positive health impacts, decreased stress and improved mood, decreased loneliness, and better communication with others [2]. SARs may be used to complement therapists in rehabilitation (e.g. [11]), or to play functional and affective roles in the lives of older adults. Care-O-bot, for example, supports independently living older adults by delivering meals and drinks [12]. The seal-like robot PARO [5, 6] is used as a social companion. Robots can also act as communication devices that connect older adults with remote caregivers (e.g. [13]).

SARs development has so far focused on two main contexts of use: the home, where robots can provide aid to independently living individuals, and institutions such as nursing homes and hospitals, where robots assist both older adults and caregivers. The development of SARs for these environments raises significant social concerns beyond the technical issues involved. Field studies of interactions between people and robots in hospitals (e.g. [14]), nursing homes (e.g. [15]), and private homes (e.g. [16]) have brought attention to the effects of workflow, individual interpretations, users’ values, and the physical environment, on the success and consequences of robots in society. This suggests that developing SARs for everyday use requires research, design, and evaluation sensitive to the social consequences and user interpretations of robots.

C. Healthcare-Related Challenges & Opportunities

Healthcare in recent years has seen a push toward patient-centered care, which views patients as the primary drivers of health and healthcare needs, in comparison to the more traditional view centering on diagnosis and treatment of disease after it occurs. An individual’s health is now commonly seen as an amalgamation of lifestyle choices, genetics, and environmental factors that accumulate over long periods of time. A person’s health status is also acknowledged as fundamental to their quality-of-life (QOL) [17], with an increasing focus on wellness, activity, and participation in health [18]. Consequently, the question for any innovative technology geared towards health-related applications is how it can ameliorate an individual’s QOL by affecting their health status over their lifespan. This is particularly true in chronic illnesses, where a cure is often not available [19], like dementia, where delaying onset is a key strategy [20]. A preventive approach to health can reduce costs and better aligns with patient preferences to minimize time spent in institutionalized settings [21].

SARs hold significant potential in supporting preventive healthcare, especially among the elderly. A majority of older adults (70% of the population from which we draw our participants) have multiple co-occurring chronic health conditions and/or are at risk of several others. Development of mental illness in older adults (e.g. clinical depression) often precipitates a significant decline in physical health, which in turn often leads to the need for institutionalized care [22]. The incidence of co-occurring disorders only increases with age [23]. SARs can be used to directly intervene in this co-occurring cycle. Research in laboratory and institutional settings suggests that interactive robots and sensors can support and enhance the social, cognitive, and physical functioning of older adults [1, 5, 6]. Similar benefits may potentially exist for older adults in their own homes before they become institutionalized and/or seriously ill. SAR-based interventions will also impact clinicians, as the introduction of in-home robots may alter how healthcare is provided within the clinic. Finally, SARs as preventative tools dovetail nicely with ongoing trends in the delivery of healthcare, particularly the focus on patient-centered care. However, bringing such potential to fruition requires an understanding of how SARs might fit into the broader sociotechnical ecosystem of the home.

III. CASE STUDY: PARTICIPATORY DESIGN WITH OLDER ADULTS WITH DEPRESSION AND THERAPISTS

A. Participatory Design for SARs Development

Along with the increasing focus on patient-centered care and prevention, the long history of using participatory design methods to develop healthcare solutions also informs our approach. Over forty years of practice and research in participatory design (PD) for information technology has shown that negotiation of the social meanings, uses, and effects of technologies throughout the design process can lead to more successful technical and social outcomes. The basic element of PD is to involve all those with a stake in the functioning of technology to participate in decisions about its design and/or implementation. One potential benefit of such involvement is that participation of users will increase the likelihood that the eventual system fits its intended use context and works well. Another is that stakeholders involved in system development are likely to feel more positively about the system than those not so involved, and will actively scaffold its deployment and use. Such an approach aligns well with the user-centered approaches to healthcare described above (Section II.C).

Technical complexity has often been used as a justification for keeping users outside of the decision-making processes regarding the design and use of robotic technologies. Ethically speaking, however, the people who will interact directly with eldercare robots should have opportunities to influence their development. Applications of PD methodologies to robotics in neighborhood communities [24] and in education [25] suggest that active participation in the design of robotic technologies can empower users with knowledge about technology, allowing them to take part in
critical discussions of the potential social consequences and meanings of new technologies [24]. Frennert, Eftring and Ostlund [26] recently used a participatory approach to robot design by having older adults evaluate life-size mock-ups in their homes to explore the potential uses and appearance of assistive robots. Ezer et al [27] found that technological experience, rather than age, was the main predictor of people’s expectations from robots, suggesting that making older adults more aware of the technical possibilities of robots through PD could also increase acceptance [28].

B. A Case Study of SARs Participatory Design

Our current project focuses on the utilization of SARs for the prevention and early management of clinical depression in independently living older adults to help reduce the need for institutionalized care. The aim is two-fold: attempting to understand user needs and potential implementation strategies through PD approaches, and exploring which PD methodologies are appropriate for co-designing assistive technologies with older adults and their therapists.

Participants include therapists and older adult patients (>55) experiencing co-occurring chronic mental (major clinical depression) and physical illness (mainly hypertension, diabetes, chronic pain, and cardiovascular disease), who receive treatment services from a large outpatient healthcare provider in rural Indiana. The patients are approximately gender-balanced (i.e. 50/50 male to female ratio). The providers see over 80,000 patients a year across 150 outpatient clinical sites in multiple states (e.g. Tennessee, Indiana, and Kentucky). Informed by prior PD studies in information and robotic technologies, we are conducting initial in-home interviews with individual participants, followed by two group workshops to study how they perceive existing SARs and what design characteristics they desire to be part of future SAR technologies, as described below.

1) In-Home Interviews

Initial semi-structured interviews are being performed with participants in their homes. The interviews involve the collection of demographic information about participants, and continue with a discussion of their current life situation and experiences, their social relationships, specific life issues they face, and current ways technology is used in their daily life. The interviews aim to provide information about participants’ general needs, to allow researchers and participants to define design goals together by identifying what affects participants’ mood positively and negatively (e.g., people, events, memories), their existing methods for coping with depression, and to give researchers a chance to understand the daily experience of participants. The interviews end with a walk-through of the participant’s home documented through field notes and photos.

2) Therapist Interviews

Along with interviewing participants in their homes, we are also interviewing five therapists about their experiences working with independently living older adults with depression to better understand their practices and needs. During the interviews, we show therapists videos and live demos of existing assistive robotic technologies and ask them to critique the robots, letting us know which aspects they see as helpful or not in their work, whether they think they would use the technologies, and what kinds of attributes future assistive technologies should have to be useful.

3) Participatory Design Workshops

We are also hosting a series of participatory design workshops to give older adults an opportunity to be active in the development of SARs, both through critiquing existing robots and developing their own interactive prototypes.

The first workshop will last 2 hours. Participants will be invited in groups of 5-8 in two separate sessions. The workshop will start with a summary of the interview findings. For the first hour, participants will watch and critique videos of assistive technologies. In the second hour, we will have live demonstrations of robots, including the PARO robotic seal (see Figure 1 below). Our main aim for this workshop is to learn how participants interpret existing technologies, relate these technologies to their own experiences and concerns,) see themselves using such technologies, and what kind of characteristics assistive technologies should have in the future. Their feedback will also be interpreted in relation to their everyday experiences, challenges, and coping mechanisms we identified during individual interviews. We will also note what kinds of tasks and questions elicit better feedback from participants (e.g. videos or live demos), how best to inspire critique, and the challenges we face in motivating participation, which will help us further develop our PD methodology for older adults. The workshops will be videotaped for more detailed analysis later on.

During the second workshop, also lasting up to 2 hours, participants will design their own assistive technology prototypes together and with the help of the researchers. The aim of this workshop is to allow participants to actively develop and try out the functions they want to see in a future SAR while balancing their desires with technical capabilities. We will also explore PD methods to help participants engage in creative thinking regarding assistive technologies. Participants will first be given a variety of familiar craft materials (e.g., cardboard, colored paper, pens) and asked to construct a low-fidelity prototype of an assistive technology they would like to have. Participants will work in groups of 2-3, and investigators will be there to assist them. Following this initial activity, we will give participants Hummingbird robotics kits (http://www.hummingbirdkit.com/) [25]. Investigators will
work with participants to see how different sensors work, i.e. how a machine might sense the world. They will then use the kits to design some interactive capabilities for their assistive technology (e.g. when it hears a voice, a part of the prototypes moves). Participants will present their designs to each other, justifying and discussing their design choices with the larger group. They will also discuss their experiences of working with the technology and possibilities for further design of the artifact, as well as its potential usefulness. We will end the workshop with a general discussion of the potential uses of assistive robotic technologies, how they can be used to address issues faced by older adults who suffer from depression, and any comments they have on the workshops they participated in.

The series of interviews and workshops described above will inform us about the current daily life and issues faced by independently living older adults with depression and co-occurring health conditions, their existing treatment and ways of coping with their condition, and their developing ideas regarding their potential use of SARs technologies.

IV. CONCLUSION

Socially assistive robots are a promising technology for preventive, patient-centered care. The ongoing project described here uses participatory design to explore the everyday experiences of and challenges facing older adults with co-occurring depression and chronic physical illness, their perceptions of SARs, and how these technologies can be used to delay the need for institutionalized care for this population. The confluence of user-centered approaches in both robotics and healthcare offers significant opportunities to explore how SARs can synergistically integrate and support ongoing changes in healthcare.

ACKNOWLEDGMENT

This research was funded by an Indiana University Consortium for Real Experiences with Public Health Information Technologies (Core PHIT) award. We thank the staff and our participants at Centerstone Outpatient Center Columbus for assisting us.

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